



TITLE:

Notes on Effective Usage of Double Exponential Formulas for Numerical Integration (Numerical Integration and Related Topics)

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Notes on effective usage of double exponential formulas
for numerical integration.

Hideo Toda and Harumi Ono

1. Introduction

We shall describe the results of numerical evaluation
of an integral

$$(1-1) \quad I = \int_a^b f(x) dx$$

using the double exponential formulas (DE formulas), and
empirical evidences derived from these results.

The DE formulas have been developed as a class of
numerical quadrature formulas by Takahashi and Mori [1] ,
and they offer one of the most powerful methods to evaluate
an improper integral on $[a, b]$, in which the integrand is
singular at one endpoint or both. Moreover, we shall show
a method to evaluate difficult integrals, where the integrand
is highly oscillating.

2. Comparison of results by some numerical integration formulas.

As a numerical comparison of formulas among DE, IMT, CADRE
and QUAD we show in Table 2-1 the number of integrand evaluations
and the relative error estimated from the following convergence
criterion (2-1) by choosing 15 test cases of Patterson [3] and
Ichida and Kiyono [4].

A convergence criterion of our program is satisfied when

$$(2-1) \quad |S_{i+1} - S_i| \leq \varepsilon |S_{i+1}|$$

where S_i is a value of DE formula with mesh size h_i , and S_{i+1}
is a value of DE formula with mesh size $h_{i+1} = h_i / 2$, and ε
is some preassigned tolerance (e.g., 10^{-9}).

2.1 DE formula and IMT formula

Table 2.1-1

DE	IMT
$I = \int_a^b f(x) dx$ $x = \phi(u)^*$	$I = \int_0^1 f(x) dx$ $x = \psi(u) = \frac{1}{Q} \int_0^u \exp\left(-\frac{1}{t} - \frac{1}{1-t}\right) dt$ $Q = \int_0^1 \exp\left(-\frac{1}{t} - \frac{1}{1-t}\right) dt$
$I = \int_{-\infty}^{\infty} f(\phi(u)) \phi'(u) du$ $\approx I_h = h \sum_{n=-\infty}^{\infty} f(\phi(nh)) \phi'(nh)$ <p>based on the fact that the trapezoidal rule gives the best result for $\int_{-\infty}^{\infty} g(u) du$ with mesh size h.</p>	$I = \int_0^1 f(\psi(u)) \psi'(u) du$ $\approx S_N = \frac{1}{N} \sum_{n=1}^{N-1} f\left(\psi\left(\frac{n}{N}\right)\right) \psi'\left(\frac{n}{N}\right)$ <p>based on Euler-Maclaurin summation formula.</p>

* where

$$(2.1-1) \quad x = \phi(u) = \tanh\left(\frac{\pi}{2} \sinh u\right) \quad \text{if} \quad I = \int_{-1}^1 f(x) dx$$

$$(2.1-2) \quad x = \phi(u) = \exp\left(\frac{\pi}{2} \sinh u\right) \quad \text{if} \quad I = \int_0^{\infty} f(x) dx$$

$$(2.1-3) \quad x = \phi(u) = \exp(u - \exp(-u)) \quad \text{if} \quad I = \int_0^{\infty} \exp(-x) f(x) dx$$

$$(2.1-4) \quad x = \phi(u) = \sinh\left(\frac{\pi}{2} \sinh u\right) \quad \text{if} \quad I = \int_{-\infty}^{\infty} f(x) dx$$

Table 2-1 Comparison of results by DE, IMT, CADRE and QUAD

	D E	IMT	CADRE	QUAD
$P_1 \int_0^1 \sqrt{x} dx = \frac{2}{3}$	44 3.3 ₁₀ -12	127 4.9 ₁₀ -13	129 1.2 ₁₀ -10*	361 2.2 ₁₀ -10*
$P_2 \int_{-1}^1 (0.92 \cosh x - \cos x) dx$ $= 1.84 \sinh 1 - 2 \sin 1$	96 1.7 ₁₀ -12	127 2.4 ₁₀ -12	33 1.3 ₁₀ -13*	37 2.1 ₁₀ -14*
$P_3 \int_{-1}^1 \frac{dx}{x^4 + x^2 + 0.9} \div 1.5822 \ 32964$	92 3.1 ₁₀ -11	127 2.8 ₁₀ -13	129 4.2 ₁₀ -12*	73 1.5 ₁₀ -12*
$P_4 \int_0^1 x^{\frac{3}{2}} dx = \frac{2}{5}$	40 1.0 ₁₀ -11	127 8.1 ₁₀ -13	529 2.7 ₁₀ -10*	163 5.0 ₁₀ -12*
$P_5 \int_0^1 \frac{dx}{1+x^4} = \frac{1}{4\sqrt{2}} \{ \log(3+2\sqrt{2}) + \pi \}$	92 2.3 ₁₀ -12	127 5.6 ₁₀ -13	65 2.1 ₁₀ -10*	73 0*
$P_6 \int_0^1 \frac{dx}{2 + \sin 10\pi x} = \frac{2}{\sqrt{3}}$	724 1.2 ₁₀ -10	509 2.2 ₁₀ -12	785 8.4 ₁₀ -12*	757 3.3 ₁₀ -13*

$P_7 \int_0^1 \frac{x}{e^x - 1} dx \doteq 0.77750 \ 46341$	48	3.4_{10}^{-12}	127	6.6_{10}^{-13}	17	$2.2_{10}^{-12}^*$	37	$2.1_{10}^{-14}^*$
$P_8 \int_{0.1}^1 \frac{\sin 100 \pi x}{\pi x} dx$	620	2.5_{10}^{-13}	509	4.1_{10}^{-16}	3505	$3.2_{10}^{-12}^*$	2773	$5.6_{10}^{-13}^*$
$P_9 \int_0^{10} \frac{50}{\pi (2500 x^2 + 1)} dx = \frac{1}{\pi} \tan^{-1} 500$	180	2.2_{10}^{-10}	255	1.5_{10}^{-11}	337	$1.3_{10}^{-11}^*$	343	$3.3_{10}^{-12}^*$
$P_{10} \int_0^\pi \frac{\cos(\cos x + 3 \sin x + 2 \cos 2x + 3 \sin 2x + 3 \cos 3x) dx}{}$	186	8.6_{10}^{-12}	127	1.2_{10}^{-12}	417	$1.5_{10}^{-12}^*$	343	$1.0_{10}^{-12}^*$
$P_{11} \int_0^1 \log x dx = -1$	44	3.9_{10}^{-13}	127	2.0_{10}^{-11}	369	$4.5_{10}^{-9}^*$	415	$5.7_{10}^{-7}^*$

The results with superscript * are due to Ninomiya's paper.

$K_1 \int_{-1}^1 \frac{2^{-\alpha}}{4^{-\alpha} + x^2} dx$ $= 2 \tan^{-1} 2^\alpha$ $\alpha = 1, 2, \dots, 31$ $\left(K_1' 2 \int_0^1 \frac{2^{-\alpha}}{4^{-\alpha} + x^2} dx \right)$	$\alpha = 1$	202	2.4 ₁₀ -13	127	2.3 ₁₀ -13	49	1.2 ₁₀ ⁻⁷ **	63	1.6 ₁₀ ⁻⁸ **
	K_1'	103	1.7 ₁₀ -14	127	7.0 ₁₀ -13				
	$\alpha = 8$	24450	2.5 ₁₀ -12	1440	3.4 ₁₀ ⁻⁸ **	567	3.0 ₁₀ ⁻⁸ **
	K_1'	204	2.0 ₁₀ -12	255	2.3 ₁₀ -13				
	$\alpha = 31$
$K_2 \int_0^1 x^\alpha dx = \frac{1}{\alpha + 1}$ $\alpha = -.1, -.2,$ $\dots, -.9, -.99$ $\left(K_2' \int_0^\infty \frac{e^{-(1+\alpha)x}}{dx} \right)$	$\alpha = -.1$	53	2.1 ₁₀ -14	127	4.5 ₁₀ -12	2452	1.0 ₁₀ ⁻⁷ **	357	1.4 ₁₀ ⁻⁶ **
	K_2'	89	7.3 ₁₀ -10						
	$\alpha = -.8$	64	7.3 ₁₀ -16	509	5.3 ₁₀ -10	3043	2.1 ₁₀ ⁻⁶ **	3297	4.7 ₁₀ ⁻⁶ **
	K_2'	185	1.4 ₁₀ -13						
	$\alpha = -.9$	2013	6.2 ₁₀ -10	509	1.7 ₁₀ -7	3532	9.5 ₁₀ ⁻² **	6699	1.2 ₁₀ ⁻⁴ **
$H_1 \int_0^1 \log \log x dx = -\gamma$	K_2'	394	2.1 ₁₀ -16						
	$\alpha = -.99$						
		48	2.2 ₁₀ -11	121	3.1 ₁₀ -11				

The results with superscript ** are due to Ichida and Kiyono [*4*], $\varepsilon = 10^{-7}$

p6

$$f(x) = \frac{2}{2 + \sin 10\pi x}$$

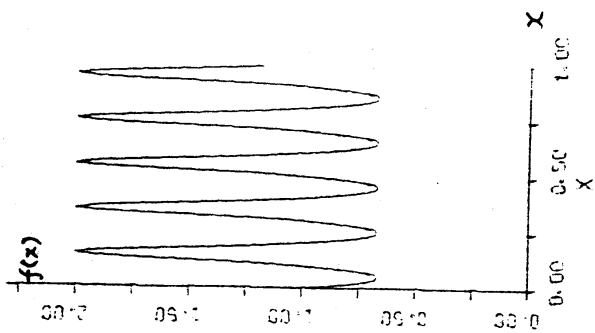


Figure 2-1

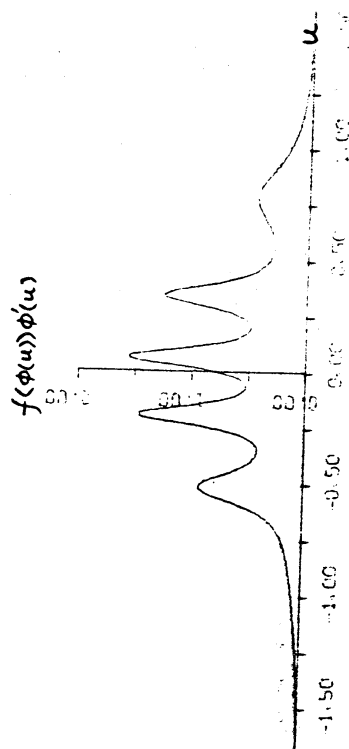


Figure 2-2

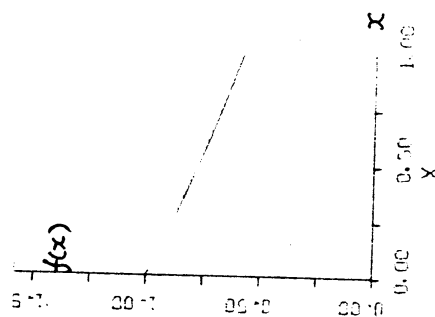


Figure 2-3

p7

$$f(x) = \frac{x}{e^x - 1}$$

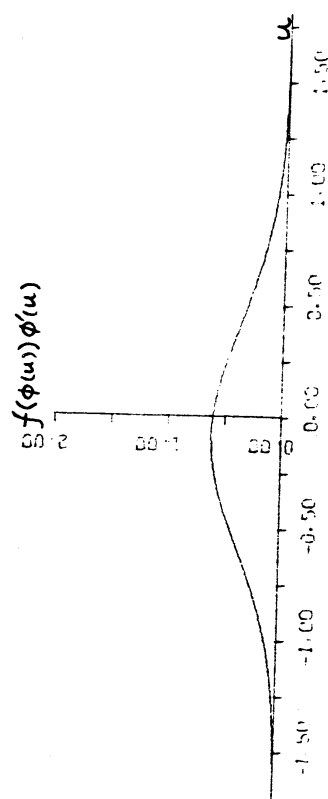


Figure 2-4

p 8

$$f(x) = \frac{\sin 100\pi x}{\pi x}$$

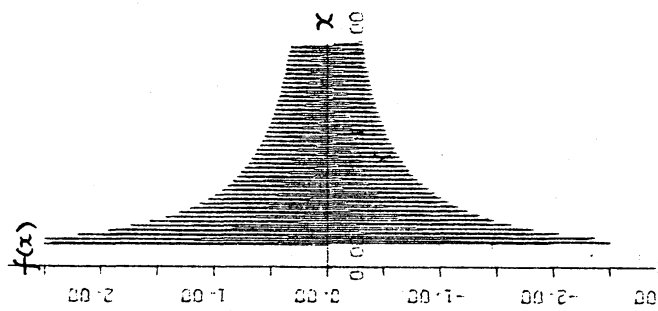


Figure 2-5

$$f(x) = \cos(\cos x + 3 \sin x + 2 \cos 2x + 3 \sin 2x + 3 \cos 3x)$$

p 10

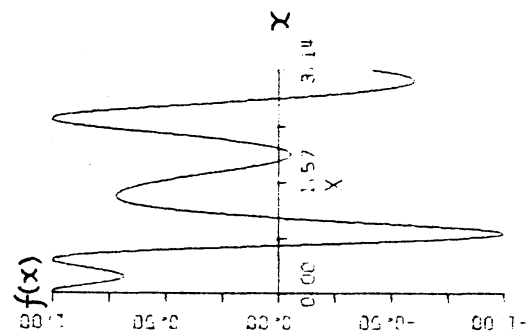


Figure 2-7

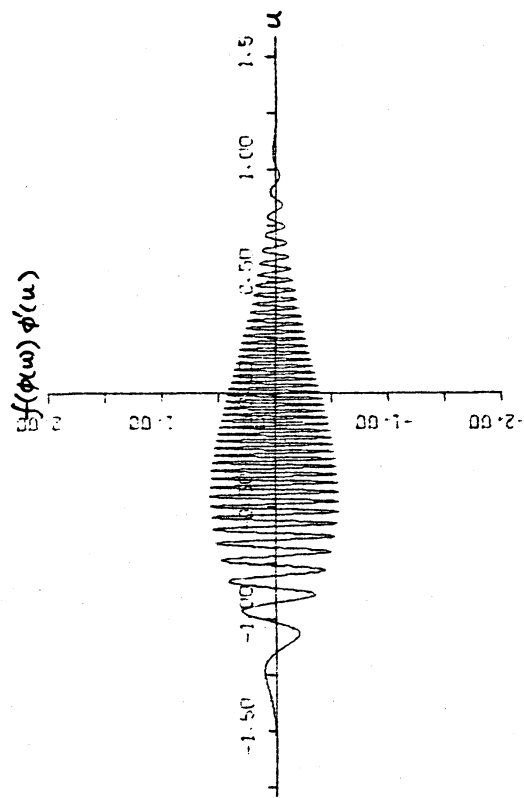


Figure 2-6

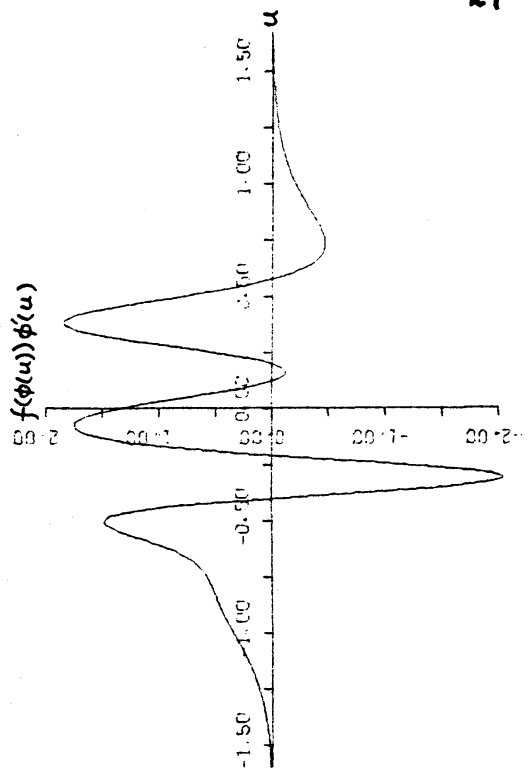


Figure 2-8

-7-

$$K_1$$

$$f(x) = \frac{2^{-\alpha}}{4^{-\alpha} + x^2}$$

$\alpha = 2, 4, 6, 8, 10$

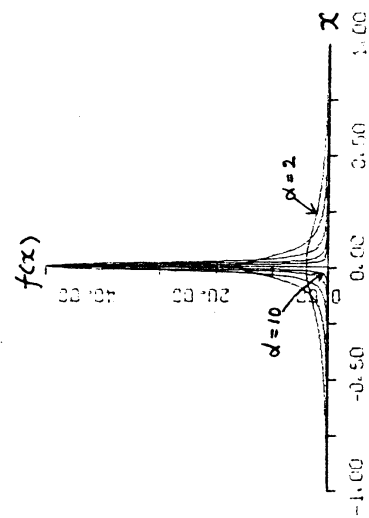
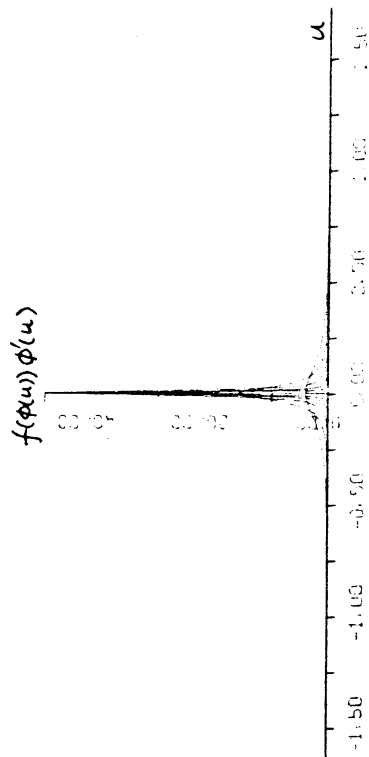


Figure 2-9

Figure 2-10-1



K_1'

$$\int_{-1}^1 f(x) dx = 2 \int_0^1 f(x) dx = \int_{-1}^1 f\left(\frac{x+1}{2}\right) dx$$

$$= \int_{-1}^1 g(x) dx$$

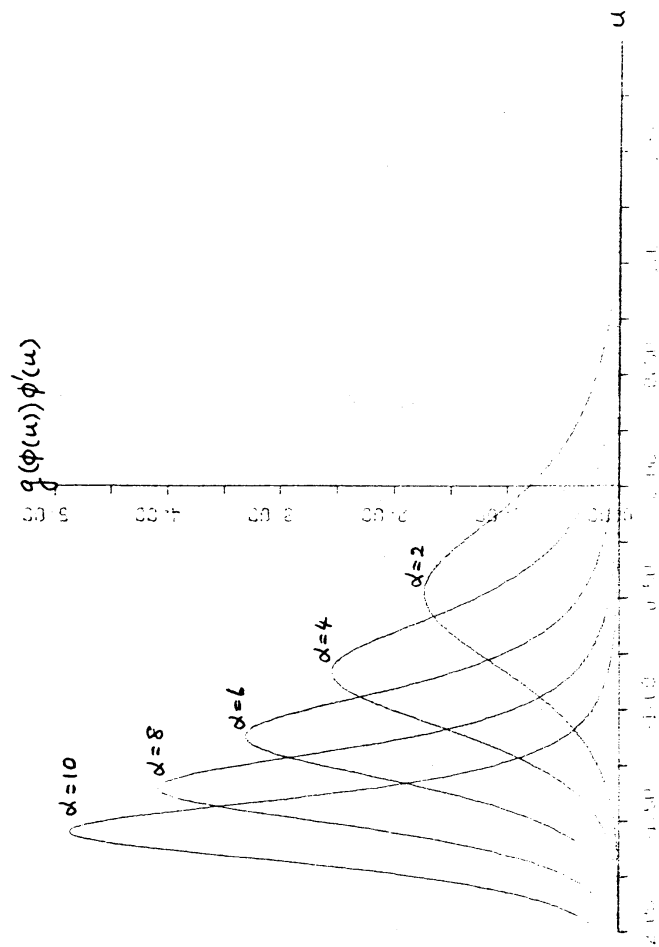


Figure 2-10-2

K 2

$$f(x) = x^\alpha, \quad \alpha = -0.1, -0.9$$

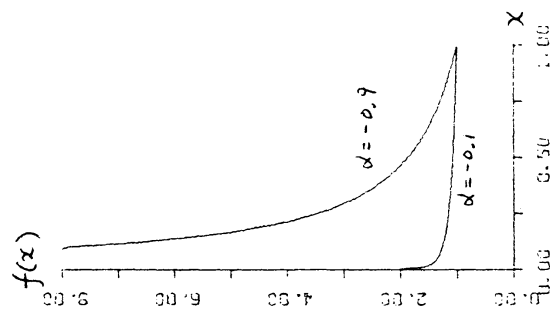


Figure 2-11

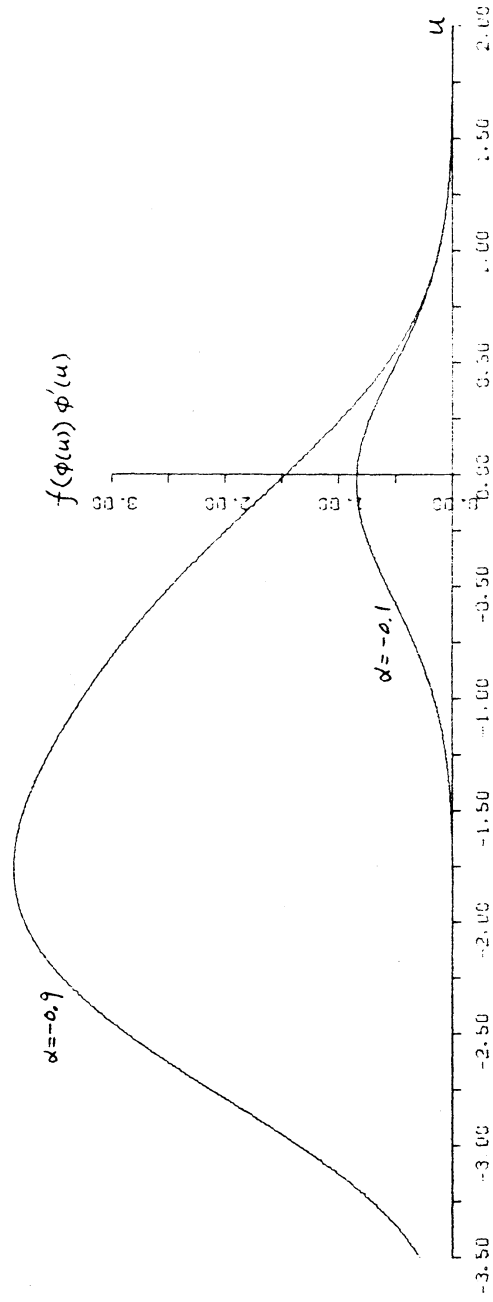


Figure 2-12

--9--

H 1

$$f(x) = \log |\log x|$$

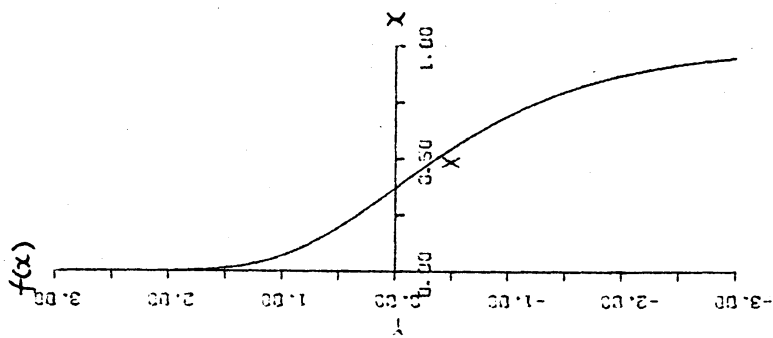


Figure 2-13

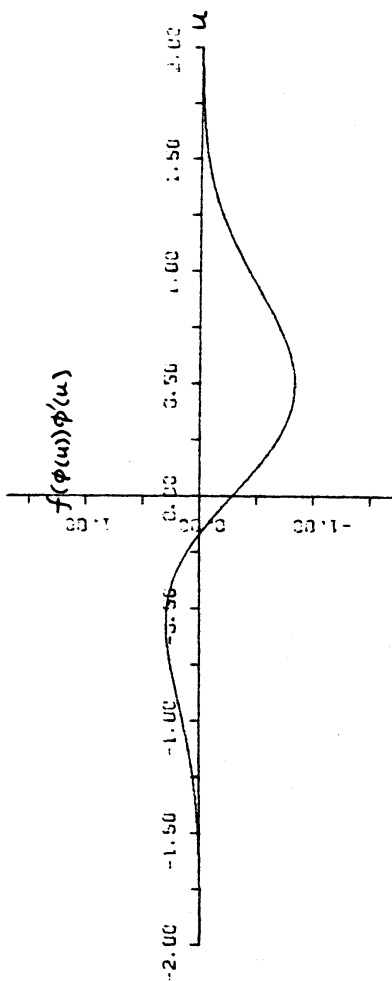


Figure 2-14-1

IMT quadrature

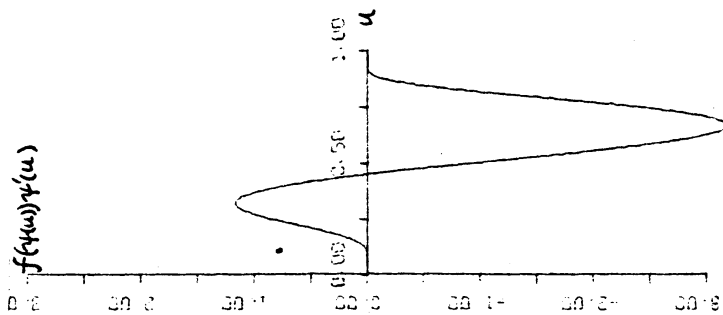


Figure 2-14-2

H 1'

$$\int_0^1 \log |\log x| dx = \int_0^\infty e^{-x} \log x dx = \int_0^\infty f(x) dx$$

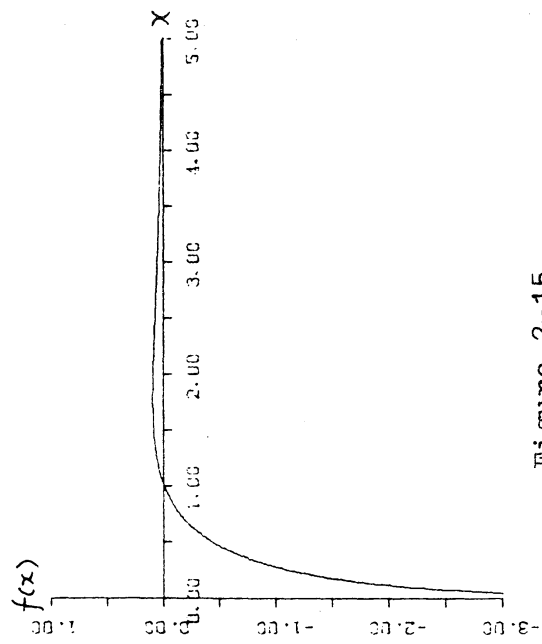


Figure 2-15

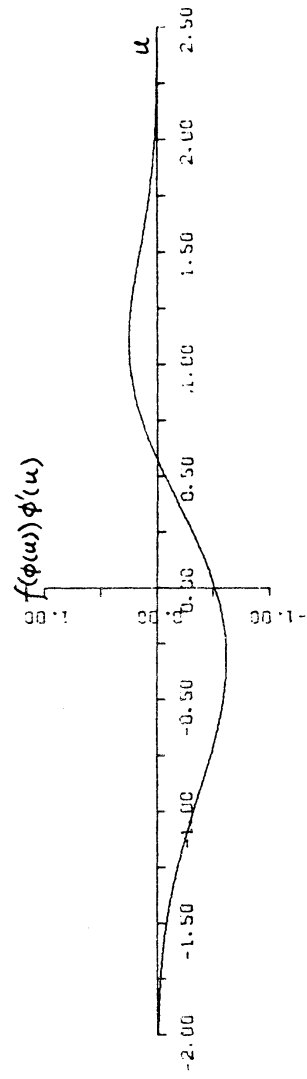


Figure 2-16

2.2 Choosing a quadrature formula

Table 2-1 supports the following statements:

- i) For integrals over finite intervals, if the integrand has no singularity through the interval, CADRE or QUAD gets an advantage over DE (P2, P5, P7).
- ii) For improper integrals over finite intervals with singularities at the endpoints of the interval, DE gets the best advantage and IMT gets the second best (P1, P4, P11).
- iii) For integrals over infinite and semi-infinite intervals, if the integrand is not regular at infinity, DE is better than all the other formulas (e.g., $\int_0^{\infty} \exp(-x) \cdot \log x \, dx$). However, if the integrand is regular at infinity, it can be reduced to the case i) by suitable change of variable (e.g., $\int_0^{\infty} \frac{1}{1+x^2} dx = \int_0^{\frac{\pi}{2}} \frac{\cos^2 \theta}{\cos^4 \theta + \sin^4 \theta} d\theta$). But even if DE may be used to evaluate the original integral, it will give slightly worse results than CADRE or QUAD.
- iv) For integrals with singularity close to the real axis in the interior of the interval (e.g., K1), it is hard to evaluate the integral with desired accuracy using any of all the methods presented here, and DE is the most unsuccessful among them. But by splitting the integral into two integrals at the real part of the singular point, it can be reduced to case ii) .

3. Notes on usage of DE formula on digital computer.

Some notes must be necessary to effective use of DE formula.

3.1 A numerical technique by Takahashi and Mori to avoid subtractive cancellation by the factor $(1+x)^\alpha(1-x)^\beta$, $\alpha, \beta < 0$.

In the case of integral $\int_{-1}^1 f(x) dx$, $f(x)$ having a factor $(1+x)^\alpha(1-x)^\beta$, $\alpha, \beta < 0$ (e.g., $f(x) = 1/\sqrt{1-x}$, $1/\sqrt{\tan((\pi/2)(1+x))}$), the number of its significant digits decreases as $x \rightarrow \pm 1$.

Thus the relative error in the $f(x)$ will be greatly increased. In such a case, following Takahashi and Mori [1] p.735, we must make the change of variable to avoid the cancellation; splitting the integral into two integrals, we have

$$(3.1-1) \quad I = \int_{-1}^1 f(x) dx = \int_{-1}^0 f(x) dx + \int_0^1 f(x) dx = I_1 + I_2$$

and we make direct substitution of $1 \pm x$ as follows:

$$(3.1-2) \quad -t = 1+x = 1 + \tanh\left(\frac{\pi}{2} \sinh u\right) = \frac{\exp\left(\frac{\pi}{2} \sinh u\right)}{\cosh\left(\frac{\pi}{2} \sinh u\right)}$$

$$t \in [-1, 0]$$

$$(3.1-3) \quad t = 1-x = 1 - \tanh\left(\frac{\pi}{2} \sinh u\right) = \frac{\exp\left(-\frac{\pi}{2} \sinh u\right)}{\cosh\left(\frac{\pi}{2} \sinh u\right)}$$

$$t \in [0, 1]$$

Then we obtain

$$(3.1-4) \quad I_1 = \int_{-1}^0 f(-1-t) dt = \int_{-\infty}^0 f(-1-t(u)) \cdot \frac{\frac{\pi}{2} \cosh u}{\cosh^2\left(\frac{\pi}{2} \sinh u\right)} du$$

$$(3.1-5) \quad I_2 = \int_0^1 f(1-t) dt = \int_0^{\infty} f(1-t(u)) \cdot \frac{\frac{\pi}{2} \cosh u}{\cosh^2\left(\frac{\pi}{2} \sinh u\right)} du$$

3.2 Note on mechanizing DE formula on digital computer.

The essence of the technique described above is to substitute $\mp \exp(\pm \frac{\pi}{2} \sinh u) / \cosh(\frac{\pi}{2} \sinh u)$ directly into $t = \mp 1-x$. Thus, it will be of no use to avoid cancellation to make the change of variable $x = -1-t$ for $x \in [-1, 0]$ and $x = 1-t$ for $x \in [0, 1]$ in library programs and to write $f(x)$ in its original form. Since the term $1+x$ will be evaluated not by $-t$ but by $1 + (-1-t)$, the loss of significance will be very large. Then we must transform $f(x)$ into the expression $g(t)$ of the independent variable $t = -1-x$ for $x \in [-1, 0]$, and $t = 1-x$ for $x \in [0, 1]$. For example,

$$f(x) = (1+x)^{-\frac{1}{2}}(1-x)^{-\frac{1}{3}}$$

we must make transformation as follows:

$$f(x) = g(t) = \begin{cases} (-t)^{-\frac{1}{2}}(2+t)^{-\frac{1}{3}} & t \in [-1, 0] \\ (2-t)^{-\frac{1}{2}}t^{-\frac{1}{3}} & t \in [0, 1] \end{cases}$$

The same situation holds for the integral $\int_a^b f(x)dx$, if $f(x)$ has a factor $(x-a)^\alpha(b-x)^\beta$, $\alpha, \beta < 0$. In this case we must transform $f(x)$ into the expression of the variable

$$t = -\frac{2}{b-a}(x-a) \text{ for } x \in [a, \frac{a+b}{2}] \text{ and } t = \frac{2}{b-a}(b-x) \text{ for } x \in [\frac{a+b}{2}, b].$$

If this transformation is very tedious, we can transform the integral into an integral over $[0, \infty)$ by suitable change of variable (e.g., $x = \exp(-t)$), and then apply (2.1-2) or (2.1-3). For H1, by the change of variable $x = \exp(-t)$, we get

$$H1' \quad I = \int_0^\infty \exp(-t) \log t \, dt$$

In this case, there is a problem how to choose the initial step size h_0 for H1. We shall consider this problem in the next section.

3.3 The initial step size h_0 .

Our starting algorithm to find M, N such that

$S_0 = \sum_{n=-M}^N f(\phi(nh_0)) \cdot \phi'(nh_0)$, where S_0 is the first approximation of I , is as follows:

Input

ε (some preassigned tolerance)

h_0 (initial step size)

Algorithm

$h \leftarrow h_0$; $S_0 \leftarrow f(\phi(0)) \cdot \phi'(0)$; $N \leftarrow 0$; $M \leftarrow 0$

for $n=1, 2, \dots$ do

if $N=0$ then $T_n \leftarrow f(\phi(nh)) \cdot \phi'(nh)$

if $|T_n| \leq |S_0| \cdot \max(\varepsilon \cdot 10^{-3}, 10^{-6})$ then $N \leftarrow n$

else $S_0 \leftarrow S_0 + T_n$

endif

endif

if $M=0$ then $U_n \leftarrow f(\phi(-nh)) \cdot \phi'(-nh)$

if $|U_n| \leq |S_0| \cdot \max(\varepsilon \cdot 10^{-3}, 10^{-6})$ then $M \leftarrow n$

else $S_0 \leftarrow S_0 + U_n$

endif

endif

endfor

next:

Thus,

$$(3.3-1) \quad |T_n| \leq |S_0| \cdot \max(\varepsilon \cdot 10^{-3}, 10^{-6})$$

$$|U_n| \leq |S_0| \cdot \max(\varepsilon \cdot 10^{-3}, 10^{-6})$$

must hold before nh_0 , $n=1, 2, \dots$, exceeds a certain threshold value which depends on representation of number by computer.

For example, in the case of H1, we have

$$\begin{aligned} I &= \int_0^1 \log |\log x| dx = \int_{-1}^1 \frac{1}{2} \log \left| \log \frac{1+x}{2} \right| dx \\ &= \int_{-1}^0 \frac{1}{2} \log \left| \log \left(-\frac{t}{2} \right) \right| dt + \int_0^1 \frac{1}{2} \log \left| \log \frac{2-t}{2} \right| dt \end{aligned}$$

where

$$-t = \frac{\exp(\frac{\pi}{2} \sinh u)}{\cosh(\frac{\pi}{2} \sinh u)} \quad t \in [-1, 0]$$

$$t = \frac{\exp(-\frac{\pi}{2} \sinh u)}{\cosh(\frac{\pi}{2} \sinh u)} \quad t \in [0, 1]$$

Since $2-t$ and 2 are considered as the same values (additive no contribution) for $nh_0 > 3.45$ with double precision arithmetic in T-56, the second integrand $\frac{1}{2} \log \left| \log \frac{2-t}{2} \right|$ is regarded as $\log 0$ (error message "not allowed").

In the case of P7, we have

$$\begin{aligned} I &= \int_0^1 \frac{x}{\exp x - 1} dx = \int_{-1}^1 \frac{1}{2} \cdot \frac{\frac{1+x}{2}}{\exp(\frac{1+x}{2}) - 1} dx \\ &= \int_{-1}^0 \frac{1}{2} \cdot \frac{-\frac{t}{2}}{\exp(-\frac{t}{2}) - 1} dt + \int_0^1 \frac{1}{2} \cdot \frac{\frac{2-t}{2}}{\exp(\frac{2-t}{2}) - 1} dt \end{aligned}$$

In the denominator of the first integral $\exp(-\frac{t}{2})$ is considered to be 1 for $nh_0 \geq 3.31$.

In both cases for large step size h_0 , our starting algorithm results in failure by evaluating $f(\phi(nh_0)) \cdot \phi'(nh_0)$ or $f(\phi(-nh_0)) \cdot \phi'(-nh_0)$ at a point nh_0 beyond the limit 3.45 or 3.31 respectively. In contrast, it can be expected that by taking h_0 small enough depending on the tolerance ε (3.3-1) can hold before nh_0 exceeds that threshold value. This is illustrated in Fig. 3.3-1.

P7-1

ERROR REQUIREMENT 0.1000E-14 HO = 0.50000

FT957W ERROR AT(020531) DIVIDE CHECK

0.50000	7	0.7774990274260581	0.7211E-05
0.25000	13	0.7775046341101479	0.2701E-11
0.12500	26	0.7775046341122483	

S = 0.7775046341122483 ER = 0.1314E-16

P7-2

ERROR REQUIREMENT 0.1000E-14 HO = 0.25000

0.25000	13	0.7775046341101479	0.2701E-11
0.12500	26	0.7775046341122483	

S = 0.7775046341122483 ER = 0.1358E-16

H1-1

ERROR REQUIREMENT 0.1000E-11 HO = 0.50000

FT911W ERROR AT(020621)	DLOG	ARG= 0.0	(ARG,LE,0)	RESULT=(MIN VALUE)
FT911W ERROR AT(020621)	DLOG	ARG= 0.0	(ARG,LE,0)	RESULT=(MIN VALUE)
0.50000	8	7	-0.2026589570990376E+56	

H1-2

ERROR REQUIREMENT 0.1000E-11 HO = 0.25000

0.25000	13	13	-0.5772156649014750	
S = -0.5772156649015324	ER = 0.9944E-13	TRUE VALUE	-0.57721566490153288608	ERROR -0.8648E-15

Figure 3.3-1

3.4 On the criterion of convergence.

Since the error term for DE formula with mesh size h is roughly estimated (Ref. [5] p.265)

$$(3.4-1) \quad |\Delta I_h| \simeq \exp(-\frac{A}{h})$$

where A is a constant, we have

$$(3.4-2) \quad |\Delta I_{\frac{h}{2}}| \simeq |\Delta I_h|^2$$

So that if we halve the mesh size, then the number of significant digits are doubled. Thus we can usually get the desired accuracy when

$$(3.4-3) \quad |S_{i+1} - S_i| \leq \sqrt{\varepsilon} |S_{i+1}|$$

holds, except in the case where the integrand oscillates (e.g., P8 and P10).

In the above-mentioned case, however, on the safe side, we should like to test whether both

$$|S_{i+1} - S_i| \leq \varepsilon |S_{i+1}|$$

and

$$|S_{i+2} - S_{i+1}| \leq \varepsilon |S_{i+2}|$$

hold as the criteria of convergence. From Fig. 3.4-1, we see that (3.4-2) does not hold until mesh size h becomes small enough.

P6

ERROR REQUIREMENT 0.1000E-14 HO = 0.50000

0.50000	7	1.145065201836647	0.3215E-01
0.25000	13	1.109398079973005	0.6951E-02
0.12500	26	1.101740303515750	0.4805E-01
0.62500E-01	52	1.157349192484848	0.2285E-02
0.31250E-01	103	1.154711000023246	0.9060E-05
0.15625E-01	205	1.154700538516411	0.1188E-09
0.78125E-02	409	1.154700538379251	

S = 1.154700538379251

ER = 0.7079E-17

TRUE VALUE

1.154700538379251529

ERROR -0.5033E-16

P8

ERROR REQUIREMENT 0.1000E-14 HO = 0.50000

0.50000	6	0.2455391953890915	0.6189E-01
0.25000	11	0.2312281657296014	0.1053E+01
0.12500	22	0.1126117247672289	0.8368E+00
0.62500E-01	44	0.6130785022273157E-01	0.5753E+00
0.31250E-01	87	0.3891818870620057E-01	0.3277E+01
0.15625E-01	173	0.9098637539166843E-02	

S = 0.9098637539166843E-02

ER = 0.3978E-16

P10

ERROR REQUIREMENT 0.1000E-14 HO = 0.50000

0.50000	7	1.873635947230349	0.1294E+01
0.25000	14	0.8168465615955236	0.2712E-01
0.12500	27	0.8396163176771946	0.1121E-02
0.62500E-01	53	0.8386763427025238	0.9651E-11
0.31250E-01	105	0.8386763426944296	

S = 0.8386763426944296

ER = 0.3249E-17

Figure 3.4-1

- 19 -

4. Difficult problems of integration

4.1 The restriction imposed by the number of bits for exponent.

The number of bits for exponent is usually taken to be 7 or 8. Then, for example, the integral to get the abscissas of IMT formula

$$I = \int_0^t \exp\left(-\frac{1}{x} - \frac{1}{1-x}\right) dx$$

$$= t \int_0^\infty \exp\left(-\frac{1}{t \exp(-x)}\right) \exp\left(-\frac{1}{1-t \exp(-x)}\right) \exp(-x) dx$$

with $t = 3/512, 2/512, 1/512$, has the value far smaller than 10^{-8} . Thus, if we wish to evaluate this integral using DE formula (2.1-3), our algorithm will fail, since (3.3-1) is not satisfied before $nh=5.5$, with this nh $x = \exp(nh - \exp(-nh))$ becomes 243.7 and $\exp(-x)$ vanishes.

Such a problem requires the use of multiple-precision arithmetic [6].

5. Conclusion

We conclude from the experiment described above that DE formulas offer a very powerful method for numerical integration, except for the special cases described in the previous section. It is recommended to use DE formulas especially for integrals over infinite or semi-infinite intervals.

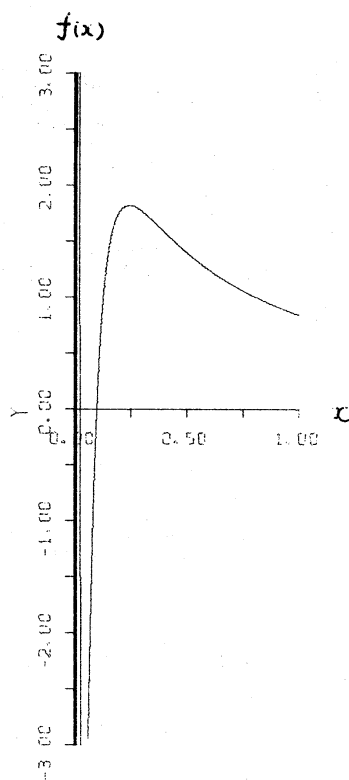
Appendix.

Dr. Rabinowitz presented the following problem when he visited ETL at Tsukuba on June 4, 1980.

$$I = \int_0^1 f(x) dx = \int_0^1 \frac{\sin \frac{1}{\sqrt{x}}}{\sqrt{x}} dx \doteq 1.00813 \ 41238 \ 139$$

at $x=0$ value=0

We will show the results obtained by DE formulas below.



LIST 10@@0170-0270

```

0170 DOUBLE PRECISION FUNCTION FM1P11(X)
0180 DOUBLE PRECISION X, T, G
0190 IF(X) 1,2,2
0200 1 T = -0.500*X
0210 GO TO 3
0220 2 T = 1.000 - 0.5*X
0230 3 CONTINUE
0240 G = DSIN(1.000/DSQRT(T)) /DSQRT(T)
0250 FM1P11 = G / 2.000
0260 RETURN
0270 END

```

*RUN

PLEASE TYPE IN H0, EPS, LIST
= 0.12500

```

0.12500 23
0.62500E-01 46
0.31250E-01 91
0.15625E-01 181
0.78125E-02 361
0.39063E-02 721
0.19531E-02 1441
0.97656E-03 2881
0.48828E-03 5761
0.24414E-03 11521
0.12207E-03 23041
0.61035E-04 46081
0.30518E-04 92161
0.15259E-04 184321
0.76294E-05 368641
0.38147E-05 737281
0.19073E-05 1474561
0.95367E-06 2949121

```

*

```

1.00-9 1
28 0.9963033435784173
56 0.9812535060125632
112 1.008041952064974
224 1.003388731021478
447 1.005907923892132
893 1.008449386893941
1785 1.007959610813495
3569 1.008295296649887
7137 1.008103976816533
14273 1.008165123910790
28545 1.008143849296904
57089 1.008135239122684
114177 1.008135329025766
228353 1.008134649610200
456705 1.008134257201770
913409 1.008134050475504
1826817 1.008134144078395
3653633 1.008134131626789

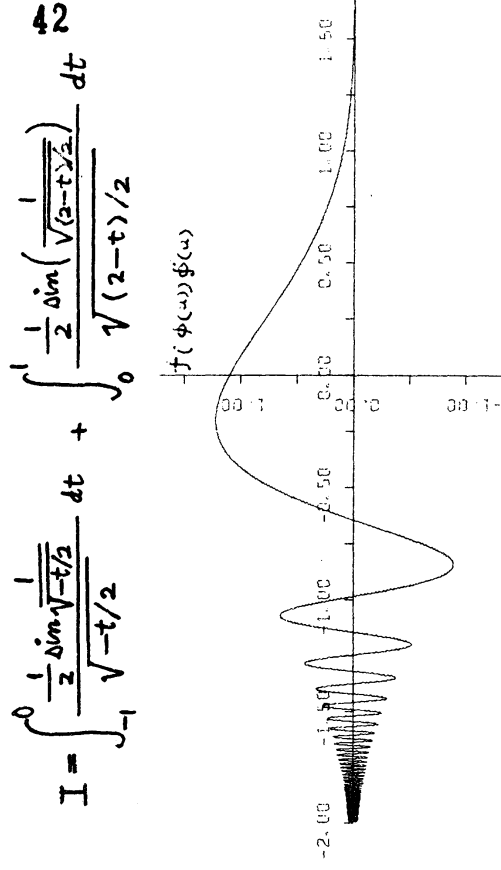
```

?

```

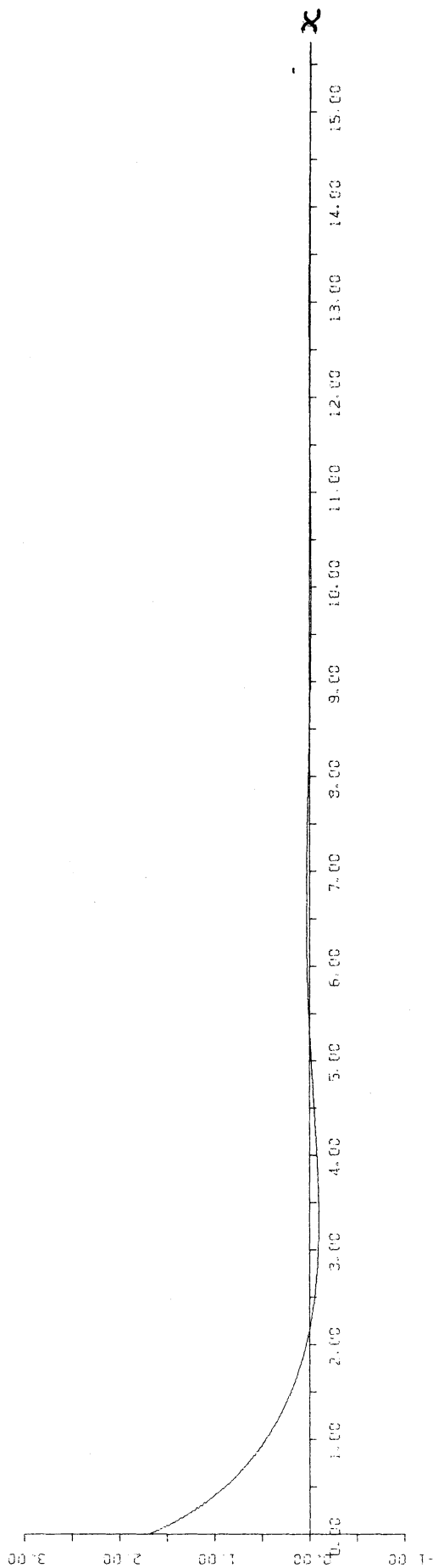
0.1534E-01
0.2657E-01
0.4638E-02
0.2504E-02
0.2520E-02
0.4859E-03
0.3329E-03
0.1898E-03
0.6065E-04
0.2110E-04
0.8541E-05
0.8918E-07
0.6739E-06
0.3892E-06
0.2051E-06
0.9285E-07
0.1235E-07

```

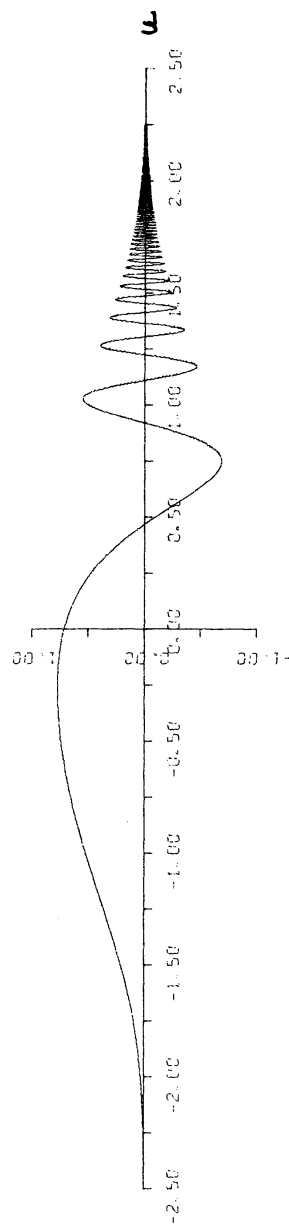


$$I = \int_0^1 \frac{\sin(\frac{1}{\sqrt{x}})}{\sqrt{x}} dx = \int_0^\infty \frac{2 \sin(1+x)}{(1+x)^2} dx \quad (\text{by Dr. Radinowit's comment})$$

$$f(x) = \frac{2 \sin(1+x)}{(1+x)^2}$$



$$f(\phi(\omega)\phi(u))$$



LIST 180-1000

```

180  DOUBLE PRECISION FUNCTION F0INF(X)
190  DOUBLE PRECISION X
200  F0INF = 2.000*DSIN(1.000*X)/(1.000+X)**2
210  RETURN
220  END

```

$$I = 2 \int_0^{\infty} \frac{\sin(1+x)}{(1+x)^2} dx$$

*RUN

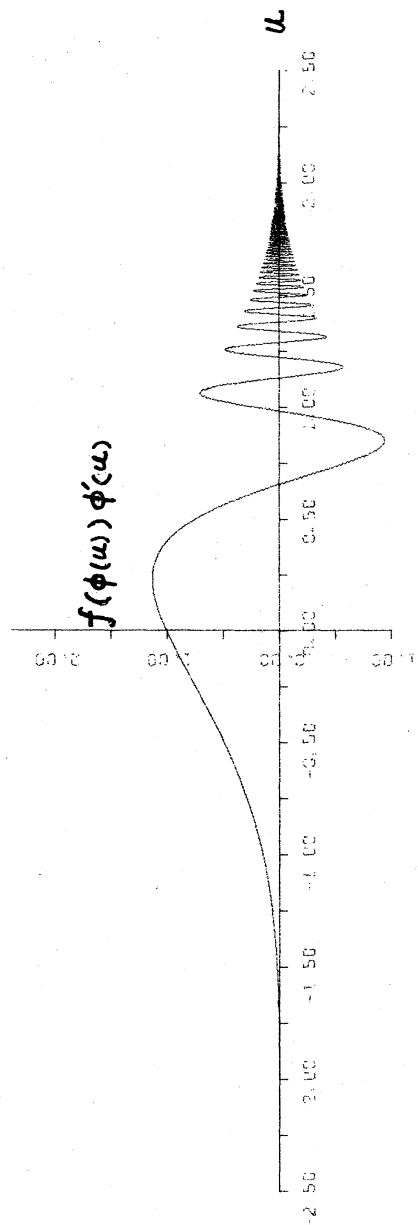
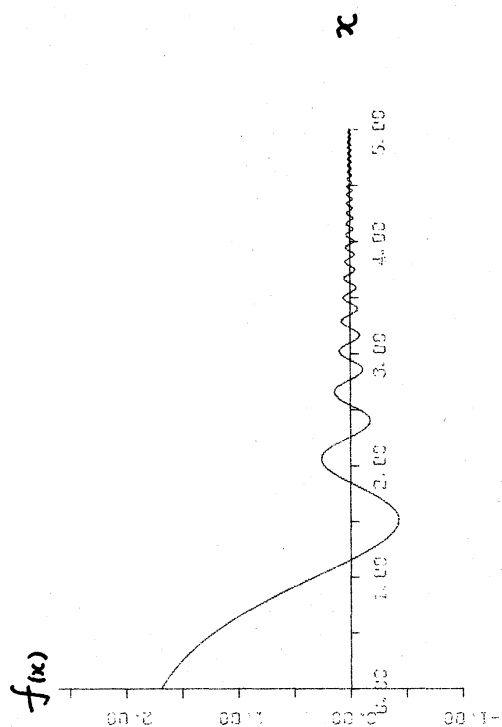
(C) INTEGRATE(F0INF, 0, INF)

PLEASE TYPE IN H0, EPS, LIST

	H0	EPS	LIST		
=	0.31250E-01	100	105	1.000068727537460	0.7562E-02
	0.15625E-01	200	210	1.007688400674151	0.9063E-03
	0.78125E-02	400	419	1.006775973599763	0.7320E-03
	0.39063E-02	800	837	1.007513512037899	0.3812E-03
	0.19531E-02	1600	1673	1.007897695988269	0.3029E-03
	0.97656E-03	3199	3345	1.008203125717950	0.2271E-04
	0.48828E-03	6397	6689	1.008180234159500	0.1012E-04
	0.24414E-03	12793	13377	1.008170029883467	0.3180E-04
	0.12207E-03	25585	26753	1.008139021682263	0.1042E-05
	0.61035E-04	51169	53505	1.008135015685097	0.3974E-05
	0.30518E-04	102337	107009	1.008133892035357	0.1115E-05
	0.15259E-04	204673	214017	1.008134156187340	0.2620E-06
	0.76294E-05	409345	428033	1.008134129054916	0.2691E-07
	0.38147E-05	818689	856065		

1.008134129054916, 0.2691E-07

$$I = \int_0^1 \frac{\sin(\frac{1}{\sqrt{x}})}{\sqrt{x}} dx = \int_0^\infty 2e^{-x} \sin(e^x) dx \equiv \int_0^\infty f(x) dx$$



$$I = \int_0^{\infty} 2 e^{-x} \sin(e^x) dx$$

LIST 180-10000

```

180      DOUBLE PRECISION FUNCTION FEXP(X)
190      DOUBLE PRECISION X, DEXPF
200      FEXP= 2.0D0*DEXP(-X)*DSIN(DEXP(X))
210      RETURN
220      END

```

*RUN

(D) INTEGRATE(FEXP, 0, INF)

PLEASE TYPE IN H0, EPS, LIST

```

= 0.12500      27      26      1.0D-9      1
0.62500E-01      54      51      1.071704042186671
0.31250E-01      107      101      1.004933608340182
0.15625E-01      213      201      0.9969797797212950
0.78125E-02      425      401      1.015120956996488
0.39063E-02      849      801      1.009720373317079
0.19531E-02      1697      1601      1.007896100079553
0.97656E-03      3393      3201      1.008593032756302
0.48828E-03      6785      6401      1.008131668867897
0.24414E-03      13569      12801      1.00811677324365
0.12207E-03      27137      25601      1.008136230970505
0.61035E-04      54273      51201      1.008135523133097
0.30518E-04      108545      102401      1.008132923350206
0.15259E-04      217089      204801      1.008134416324451
0.76294E-05      434177      409601      1.008133909877286
0.38147E-05      868353      819201      1.008134085382540
0.19073E-05      1736705      1638401      1.008134103770320
0.95367E-06      3473409      3276801      1.008134109726709

```

*↑

BREAK

References

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